

I'm not robot!

most of all agricultural areas and the ground plans of existing buildings. Additionally information as street names and the usage of buildings (e.g. garage, residential building, office block, industrial building, church) is provided in the form of text symbols. At the moment the Digital Cadastral map is built up as a database covering an area, mainly composed by digitizing preexisting maps or plans. Cost Terrestrial laser scan devices (pulse or phase shift) + processing software are available at a price of €150.000. Some less precise devices (as the Trimble TX) cost around €75.000. Terrestrial lidar systems cost around €300.000. Systems using regular still cameras mounted on RC helicopters (Photogrammetry) are also possible, and cost around €25.000. Systems that use still cameras with balloons are even cheaper (around €2.500), but require additional manual processing. As the manual processing takes around 1 month of labor for every day of taking pictures, this is still an expensive solution in the long run. Obtaining satellite images is also an expensive endeavor. High resolution stereo images (0.5 m resolution) cost around €11.000. Image satellites include Quickbird, Ikonos. High resolution monoscopic images cost around €5.500. Somewhat lower resolution images (e.g. from the CORONA satellite; with a 2 m resolution) cost around €1.000 per 2 images. Note that Google Earth images are too low in resolution to make an accurate 3D model.[39] Reconstruction Main article: 3D reconstruction From point clouds The point clouds produced by 3D scanners and 3D imaging can be used directly for measurement and visualisation in the architecture and construction world. From models Most applications, however, use instead polygonal 3D models. NURBS surface models, or editable feature-based CAD models (aka solid models). Polygon mesh models: In a polygonal representation of a shape, a curved surface is modeled as many small faceted flat surfaces (think of a sphere modeled as a disco ball). Polygon models—also called Mesh models, are useful for visualisation, for some CAM (i.e., machining), but are generally "heavy" (i.e., very large data sets), and are relatively un-editable in this form. Reconstruction to polygonal model involves finding and connecting adjacent points with straight lines in order to create a continuous surface. Many applications, both free and nonfree, are available for this purpose (e.g. GigaMesh, MeshLab, PointCab, kubit PointCloud for AutoCAD, Reconstructor, imagemodel, PolyWorks, Rapidform, Geomagic, Imageware, Rhino 3d etc.). Surface models: The next level of sophistication in modeling involves using a quill of curved surface patches to model the shape. These might be NURBS, T-Splines or other curved representations of curved topology. Using NURBS, the spherical shape becomes a true mathematical sphere. Some applications offer patch layout by hand but the best in class offer both automated patch layout and manual editing. These patches have the advantage of being lighter and more manipulable when exported to CAD. Surface models are somewhat editable, but only in a sculptural sense of pushing and pulling to deform the surface. This representation lends itself well to modelling organic and artistic shapes. Providers of surface modellers include Rapidform, Geomagic, Rhino 3D, Maya, T-Splines etc. Solid CAD models: From an engineering/manufacturing perspective, the ultimate representation of a digitised shape is the editable, parametric CAD model. In CAD, the sphere is described by parametric features which are easily edited by changing a value (e.g., centre point and radius). These CAD models describe not simply the envelope or shape of the object, but CAD models also embody the "design intent" (i.e., critical features and their relationship to other features). An example of design intent not evident in the shape alone might be a brake drum's lug bolts, which must be concentric with the hole in the centre of the drum. This knowledge would drive the sequence and method of creating the CAD model; a designer with an awareness of this relationship would not design the lug bolts referenced to the outside diameter, but instead, to the center. A modeler creating a CAD model will want to include both Shape and design intent in the complete CAD model. Vendors offer different approaches to getting to the parametric CAD model. Some export the NURBS surfaces and leave it to the CAD designer to complete the model in CAD (e.g., Geomagic, Imageware, Rhino 3D). Others use the scan data to create an editable and verifiable feature based model that is imported into CAD with full feature tree intact, yielding a complete, native CAD model, capturing both shape and design intent (e.g. Geomagic, Rapidform). For instance, the market offers various plug-ins for established CAD-programs, such as SolidWorks, Xtrac3D, DesignWorks and Geomagic for SolidWorks allow manipulating a 3D scan directly inside SolidWorks. Still other CAD applications are robust enough to manipulate limited points or polygon models within the CAD environment (e.g., CATIA, AutoCAD, Revit). From a set of 2D slices 3D reconstruction of the brain and eyeballs from CT scanned DICOM images. In this image, areas with the density of bone or air were made transparent, and the slices stacked up in an approximate free-space alignment. The outer ring of material around the brain are the soft tissues of skin and muscle on the outside of the skull. A black box encloses the slices to provide the black background. Since these are simply 2D images stacked up, when viewed on edge the slices disappear since they have effectively zero thickness. Each DICOM scan represents about 5 mm of material averaged into a thin slice. CT, industrial CT, MRI, or micro-CT scanners do not produce point clouds but a set of 2D slices (each termed a "tomogram") which are then 'stacked together' to produce a 3D representation. There are several ways to do this depending on the output required: Volume rendering: Different parts of an object usually have different threshold values or greyscale densities. From this, a 3-dimensional model can be constructed and displayed on screen. Multiple models can be constructed from various thresholds, allowing different colours to represent each component of the object. Volume rendering is usually only used for visualisation of the scanned object. Image segmentation: Where different structures have similar threshold/greyscale values, it can become impossible to separate them simply by adjusting volume rendering parameters. The solution is called segmentation, a manual or automatic procedure that can remove the unwanted structures from the image. Image segmentation software usually allows export of the segmented structures in CAD or STL format for further manipulation. Image-based meshing: When using 3D image data for computational analysis (e.g. CFD and FEA), simply segmenting the data and meshing from CAD can become time-consuming, and virtually intractable for the complex topologies typical of image data. The solution is called image-based meshing, an automated process of generating an accurate and realistic geometrical description of the scan data. From laser scans Laser scanning describes the general method to sample or scan a surface using laser technology. Several areas of application exist that mainly differ in the power of the lasers that are used, and in the results of the scanning process. Low laser power is used when the scanned surface doesn't have to be influenced, e.g. when it only has to be digitised. Confocal or 3D laser scanning are methods to get information about the scanned surface. Another low-power application uses structure light projection systems for solar cell flatness metrology.[40] enabling stress calculation throughout in excess of 2000 wafers per hour.[41] The laser power used for laser scanning equipment in industrial applications is typically less than 1W. The power level is usually on the order of 200 mW or less but sometimes more. From photograms See also: Photogrammetry 3D data acquisition and object reconstruction can be performed using stereo image pairs. Stereo photogrammetry or photogrammetry based on a block of overlapped images is the primary approach for 3D mapping and object reconstruction using 2D images. Close-range photogrammetry has also matured to the level where cameras or digital cameras can be used to capture the close-look images of objects, e.g., buildings, and reconstruct them using the very same theory as the aerial photogrammetry. An example of software which could do this is Vexcel FotoG 5.[42][43] This software has now been replaced by Vexcel GeoSynth.[44] Another similar software program is Microsoft Photosynth.[45][46] A semi-automatic method for acquiring 3D topologically structured data from 2D aerial stereo images has been presented by Sisi Zlatanova.[47] The process involves the manual digitizing of a number of points required for automatically reconstructing the 3D objects. Each reconstructed object is validated by superimposition of its wire frame graphics in the stereo model. The topologically structured 3D data is stored in a database and are also used for visualization of the objects. Notable software used for 3D data acquisition using 2D images include e.g. Agisoft Metashape,[48] RealityCapture,[49] and ENSAIS Engineering College TIPHON (Traitement d'Image et PHOtogrammétrie Numérique).[50] A method for semi-automatic building extraction together with a concept for storing building models alongside terrain and other topographic data in a topographical information system has been developed by Franz Rottensteiner. His approach was based on the integration of building parameter estimations into the photogrammetry process applying a hybrid modeling scheme. Buildings are decomposed into a set of simple primitives that are reconstructed individually and are then combined by Boolean operators. The internal data structure of both the primitives and the compound building models are based on the boundary representation methods[51][52] Multiple images are used in Zeng's approach to surface reconstruction from multiple images. A central idea is to explore the integration of both 3D stereo data and 2D calibrated images. This approach is motivated by the fact that only robust and accurate feature points that survived the geometry scrutiny of multiple images are reconstructed in space. The density insufficiency and the inevitable holes in the stereo data should then be filled in by using information from multiple images. The idea is thus to first construct small surface patches from stereo points, then to progressively propagate only reliable patches in their neighborhood from images into the whole surface using a best-first strategy. The problem thus reduces to searching for an optimal local surface patch going through a given set of stereo points from images. Multi-spectral images are also used for 3D building detection. The first and last pulse data and the normalized difference vegetation index are used in the process.[53] New measurement techniques are also employed to obtain measurements of and between objects from single images by using the projection, or the shadow as well as their combination. This technology is gaining attention given its fast processing time, and far lower cost than stereo measurements.[citation needed] Applications Space experiments 3D scanning technology has been used to scan space rocks for the European Space Agency.[54][55] Construction industry and civil engineering Robotic control: e.g. a laser scanner may function as the "eye" of a robot.[56][57] As-built drawings of bridges, industrial plants, and monuments Documentation of historical sites[58] Site modelling and lay outing Quality control Quantity surveys Payload monitoring [59] Freeway reconstruction Establishing a bench mark of pre-existing shape/rate in order to detect structural changes resulting from exposure to extreme loadings such as earthquake, vessel/truck impact or fire. Create GIS (geographic information system) maps[60] and geomatics. Subsurface laser scanning in mines and karst voids.[61] Forensic medicine[62] Design process Increasing accuracy working with complex parts and shapes. Coordinating product design using parts from multiple sources, updating old parts with those from more current technology. Replacing missing or older parts. Creating cost savings by allowing as-built design services, for example in automotive manufacturing plants. "Bringing the plant to the engineers" with web shared scans, and Saving travel costs. Entertainment 3D scanners are used by the entertainment industry to create digital 3D models for movies, video games and leisure purposes.[63] They are heavily utilized in virtual cinematography. In cases where a real-world equivalent of a model exists, it is much faster to scan the real-world object than to manually create a model using 3D modeling software. Frequently, artists sculpt physical models of what they want and scan them into digital form rather than directly creating digital models on a computer. 3D photography 3D selfie in 1:20 scale printed by Shapeways using gypsum-based printing, created by Madurodam miniature park from 2D pictures taken at its Fantastron photo booth. Fantastron 3D photo booth at Madurodam 3D scanners are evolving for the use of cameras to represent 3D objects in an accurate manner.[64] Companies are emerging since 2010 that create 3D portraits of people (3D figurines or 3D selfie). An augmented reality menu for the Madrid restaurant chain 80 Degrees[65] Law enforcement 3D laser scanning is used by the law enforcement agencies around the world. 3D models are used for on-site documentation of:[66] Crime scenes Bullet trajectories Bloodstain pattern analysis Accident reconstruction Bombings Plane crashes, and more Reverse engineering Reverse engineering of a mechanical component requires a precise digital model of the objects to be reproduced. Rather than a set of points a precise digital model can be represented by a polygon mesh, a set of flat or curved NURBS surfaces, or ideally for mechanical components, a CAD solid model. A 3D scanner can be used to digitise free-form or gradually changing shaped components as well as prismatic geometries whereas a coordinate measuring machine is usually used only to determine simple dimensions of a highly prismatic model. These data points are then processed to create a usable digital model, usually using specialized reverse engineering software. Real estate Land or buildings can be scanned into a 3D model, which allows buyers to tour and inspect the property without having to be present at the property. [67] There is already at least one company providing 3D-scanned virtual real estate tours.[68] A typical virtual tour Archived 2017-04-27 at the Wayback Machine would consist of dollhouse view, as well as a floor plan. Virtual/remote tourism The environment at a place of interest can be captured and converted into a 3D model. This model can then be explored by the public, either through a VR interface or a traditional "2D" interface. 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